in-l~lip,ht Calibration and Validation of the Airborne Visible/Infrared Imaging Spectrometer (A VIRIS)

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ABSTRACT

Calibrated spects, acquired remotely as images allow determination of surface and atmospheric properties based on absorption and scattering expressed in the spectra. AVIRIS measures spectra as images in the solar effected portion of the electro-magnetic spectrum. To use these spectra for scientific researcharld applications, the calibration of the spectra must be known at the time of measurement in flight. To validate the calibration of AVIRIS in flight, an in-flight calibration experiment was performed for an over-flight on the 9-May 1995 at Ivanpah Playa, CA. in-situ measurements of the atmosphere and surface at a calibration target were measured. These measurements were used to constrain a adiative transfer code and predict the total upwelling spectral radiance incidental AVIRIS. This prediction was compared to the radiance measured by AVIRIS for the calibration target. At a greement of 96.5 % was determined. The in-flight, signal-to noise was determined and shown to have more than doubled over the previous year.

INTRODUCTION

Calibrated spectra acquired remotely as images, allowed determination of surface and atmospheric properties, based on molecular absorption and constituent scattering characteristics. AVIRIS measures images of 11 by up to 100 km at 20 by 20 spatial resolution the consist of spectra from 400 to 2500 nm al 10 nm intervals. The spectral, radiometric and spatial characteristics of AVIRIS are calibrated in the laboratory (Chrien, 1990, 1996) prior to each flight season.

in order to be used for scientific research and applications, the calibration of AVIRIS must be valid at the time spectra are measured from the ER-2 airborne platform. The operational environment inside the Q-bay of the ER-2 at 20 km altitude is different from that in the AVIRIS laboratory.

in-flip, ht calibration experiment methodologies were developed for AVIRIS to confirm the accuracy of AVIRIS calibration in light (Conelet al., 1988; Greenet al., 1988, 1990, 1992, 1993, 1995). In these experiments the surface and atmosphere at a homogeneous ground calibration site is determined within saturneasurements. These measurements are used to constrain MOI TRAN3 (Kneizys, 1987; Bert 1989; Anderson, 1995) radiative transfer code and predict the spectral radiance incident at AVIRIS. Comparison and analysis of the predicted and AVIRIS measured radiance, is used to calibrate and validate the performance of AVIRIS in flight.

This paper describes the calibration to get, measurements, analysis and results from the inflight calibration experiment at Ivan pale Plya in 19°5.

MEASUREMENTS

On 9 May 1995, an in-flight calibration experiment was held at Ivanpah Playa, California, located 100 km south of Las Veras, Nevada at 35.5 50 degrees north latitude and

115.3990 degrees west longitude. Ivanpab Playais a drylake bed approximately 3 km by 15 km in size at 740 m elevation.

A calibration target was designated on a portion of the playa surface based on visually apparent homogeneity. The target was 40 by 200" in (2 by 10 AVIRIS spatial resolution elements). The long axis of the target was oriented in the AVIRIS flisht-line direction and demarked by blue tarps at each end of the target

At the calibration targetan automated sunphotometer was used to collect data from sunrise through the time of the AVIRIS data acquisition. The sunphotometer measures data at 370, 400, 440, 520, 620, 6'70, 780,870,940, 1 030 nm wavelength. These calibrated measurements were used to derive instantaneous optical depths through the day as shown in Figure 1. Figure 2 shows the water \ aport determined from 940 nm sun photometer measurements (Reagan et al., 1987, Bruegge et al., 1990). Some circus cloud affected the measurements around 10 am local time.

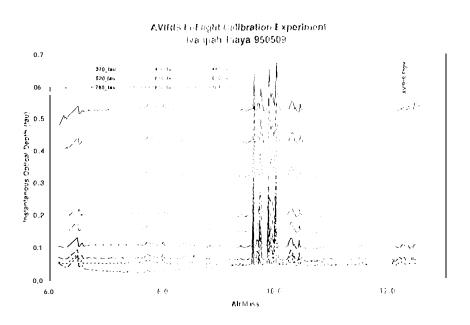


Figure 1. Derived optical depths of the non-water vapor measurements of the sun photometer.

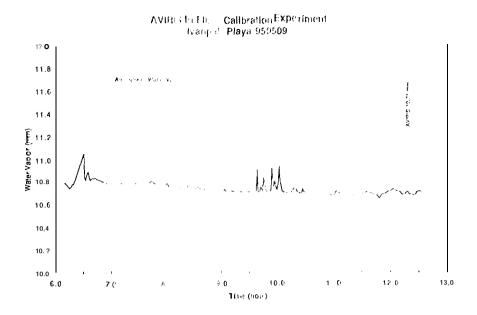


Figure 2. The water vapm abundance determined from the 940nm sun photometer measurements.

During the time of the AV11<1S data equisition, the surface spectral reflectance was measured using a field spectrometer that covers the AVIRIS spectral range. A total of 160 measurements were acquired. These measurements were evenly spaced over the target and averaged to determine the calibration targets partial reflectance as shown in Figure 3.

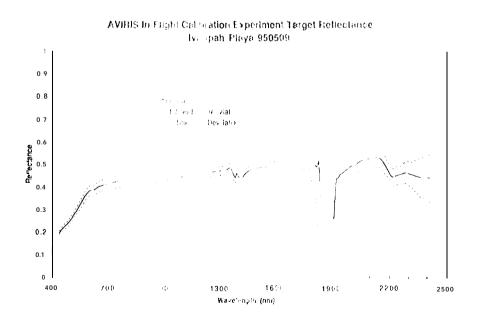


Figure 3. Calibration target spectral reflectance. The average and standard deviation are shown.

At 19.19 hours UTC AVIRIS acquired data over the Ivanpah Playa calibration target. Figure 4 shows an image of Ivanpah Playatrom 647.7 nm wave.lclly,[II. The enhance image in Figure 5 shows the two dark blue demarcation on the left edge of the playa one third of the way up the image. The uncalibrated AVIRIS spectra extracted from calibration target are shown in Figure 6.

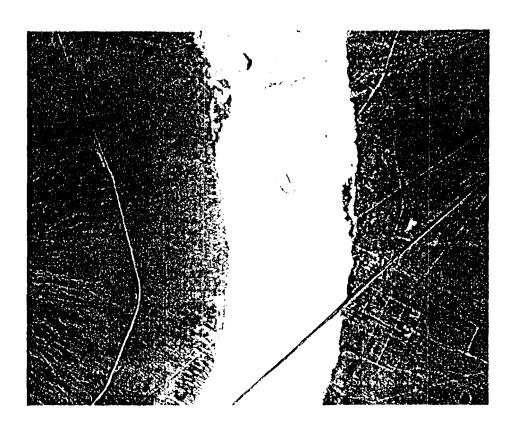


Figure 4. AVIRIS image of Ivanpah Playa from 647.7 nm.



Figure 5. Enhanced Ivanpah Playa image showing the two calibration target tarps on the left edge of the playa one third of the way up the image.

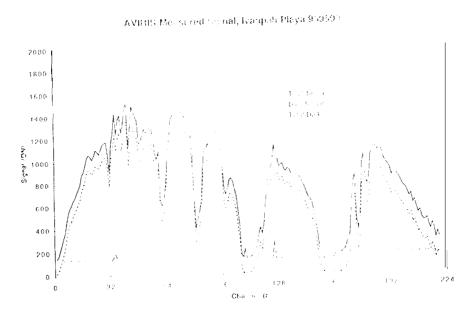


Figure 6. AVIRIS signal from the calibration target. The total signal, dark signal and dark subtracted signal are shown.

ANALYSIS

optical depths calculated at the time of the AVIRIS over pass were used to constrain the aerosol model used in the M()] M AN3 for the calibration experiment. The measured and modeled optical depths are shown in agric 7. These optical depths in conjunction with the surface spectral reflectance and atmospheric water vapor were used to constrain MODTRAN3 for the time of AVIRIS data acquisition. An updated exo-atmospheric solar irradiance spectrum (Green, 1993; Gao, 1995) was used in MODTRAN3. The MODTRAN3 predicted upwelling radiance for the calibration target is shown in Figure 8.

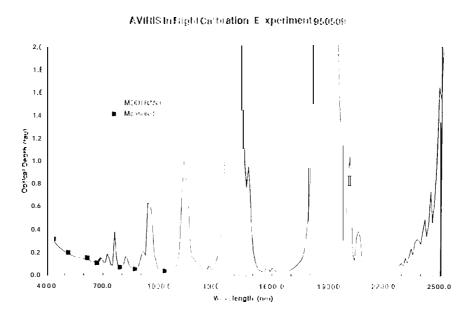


Figure 7. Measured and MODTRAN3 model of optical depths of the Ivanpah Playa calibration experiment.

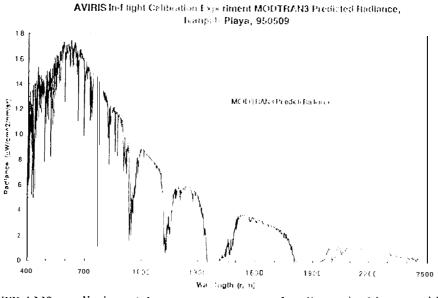


Figure 8, MODTRAN3 prediction of the upwelling spectral radiance incident at AVIRIS.

AV11<1S signal spectra were cal brated Green et al, 1992) with the laboratory determined radiometric calibration coefficients and spectral calibration (Chrien 1990; Chrien 1996). AVIRIS on-board calibrator coefficients were derived as the ratio of the in-flight on-board calibrator signal to the signal at the time of laboratory calibration (Green 1993). These on-Board calibrator coefficients are shown in Figure 9 and were applied to the AVIRIS calibration target data.

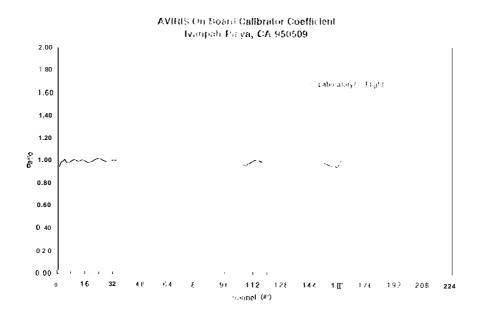


Figure 9. AVIRIS on-board calibrator coefficients. These coefficient compensate for small changes in AVIRIS performance from the laboratory to the in-flight condition.

RESULTS

The MODTRAN3 predicted spectrum convolved to AVIRIS spectral response functions and the AVIRIS laboratory calibrated spectrum are shown in Figure 10. The average absolute agreement across the spectral range was 96.5% for this experiment. The spectral regions of near-zero radiance at 1400 and 1900nm were excluded. This result is improved over the 1994 in-flight calibration experiment result of 95.3%. The disagreement was attributed to the in-situ measurements, the MODTRAN3 model, the AVIRIS and to the calibration standards. Figure 11 shows the AVIRIS to MODTRAN3 ratio for the calibration target. In this ratio disagreement occurs in the 400 nm region and nearthe atmospheric absorptions of watt. J vapor, oxygen and carbon dioxide. These discrepancies are attributed touncertainties in the MODTRAN3 model in AVIRIS spectral calibration. Nevertheless, the agreement between the MODTRAN3 prediction and the AVIRIS measurement is within 4% and this experiment initially validates the performance of AVIRIS in flight in 1995.

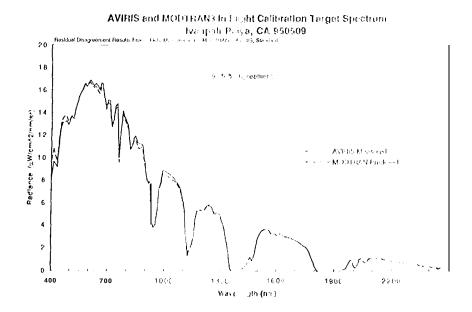


Figure 10. Comparison of the MODTRAN3 predicted and AVIRIS measured upwelling spectral radiance for the calibration target.

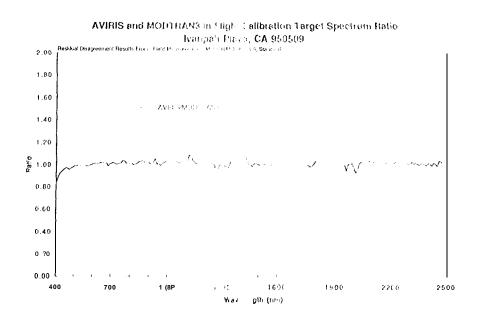


Figure 11. Calibration target ratio of AVIRISto MODTRAN3.

in-flight radiometric precision (signal-to-noise ratio) was determined with data from this calibration experiment. Noise was estimated as the standard deviation of the dark signal measured at the end of each image line. The AVIRIS signal spectrum was extracted from the calibration target. The conversion factor of photons to signal was used to estimate the additional

pholon-noise for the calibration target. The photon-noise and dark-signal noise were root-sum-squared. The extracted signal was scaled to the AVIRIS reference radiance (Green et al., 198\$) and divided by the noise to give the AVIRIS inflight signal-to-noise ratio for 1995. This signal-to-noise is improved by more than a factor of two compared to that of 1994 as shown in Figure 12. AVIRIS signal-to-noise is greater than 500; lovermuch of the spectral range. A calculation of noise- ccluivalent-del (a-radiance was also performed for a dark target and is shown in Figure 13. The noise- equivalent-del ta-radiance expression uncertainty in radiance for each AVIRIS spectrum.

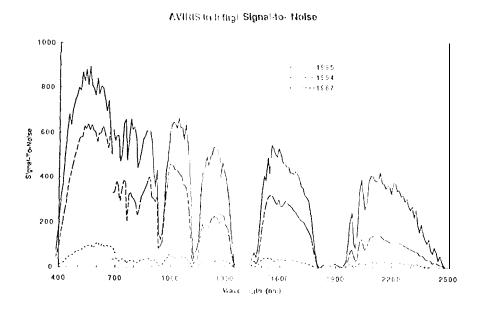


Figure 12. AVIRIS signal-to-noise for the 1995 in-flight calibration experiment.

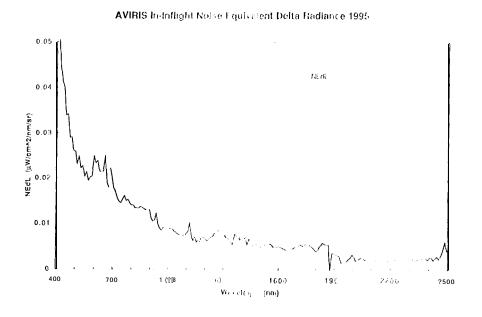


Figure 13. AVIRIS noise-equivalent delta radiance for 1995.

Additional analysis was performed to investigate the homogeneity of Ivanpah Playa at the AVIRIS spatial resolution. An images was produced of the ratio of the average to the standard deviation for all 10 by 10 spatial elements in the AVIRIS image. This image was produced from the sum of 20 AVIRIS channels in the visible II) suppress the influence of AVIRIS noise. The resulting image is shown in 1 figure 14 For 10 by 1() area at AVIRIS 20 by 20 m spatial resolution the homogeneity ranges from nearzero to 500: 1. All the calibration target values of 100:1 are found, This analysis shows that relatively few in-situme as mements are required to characterize the surface of Ivanpah Playa. However, the surface is not homogeneous enough to estimate the signal-lo-noise of AVIRIS which sgreater than 1 (100:" Importions of the spectrum.

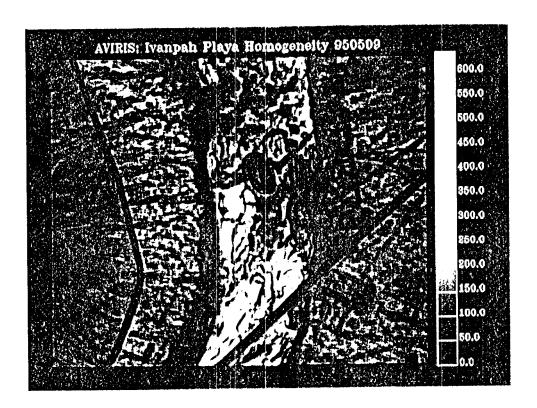


Figure 14. Ivanpah Playa homogeneity map for the 9th of May 1995.

CONCLUSION

An in-flight calibration experimentwas held at Ivanpah Playaon the 9th of May 1995. Concurrent in-situ and AVIRIS measurements were acquired for a calibration target on the homogenous playa surface. The MODTRAN adiative transfer code was constrained by the insitu measurements to predict the total upwelling spectral radiance incident at AVIRIS. This prediction was compared with the AVIRIS measured (calibrated based on the laboratory and onboard calibrator coefficients) spectrum j)~11 the calibration target. A comparison showed 96,5 % agreement with the remaining 3.5 % attributed to the in-situ measurements, MODTRAN3, AVIRIS and the calibration standards. The in! light precision of AVIRIS was assessed. Across the spectral range the AVIRIS precision was more than double that of any previous year, This experiment validates the calibration of AVIRIS in flight in 1 995. The level of calibration and

precisionachieved supports use of AVIRIS101scientific1esearchandapplications based on the absorption and scattering characteristics of theatmosphere and surface expressed in the spectra.

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